

# Lecture 9

## ARMA Models: Properties, Identification, and Estimation

Reading: Bowerman, O'Connell, and Koehler (2005): Chapter 9.2-9.4; Chapter 10.1; Cryer and Chen (2008): Chapter 4.4-4.6; Chapter 6.1-6.3

MATH 4070: Regression and Time-Series Analysis

Whitney Huang  
Clemson University

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

Notes

---

---

---

---

---

---

---

---

### Agenda

- 1 Properties of ARMA Models: Stationarity, Causality, and Invertibility
- 2 Tentative Model Identification Using ACF and PACF
- 3 Parameter Estimation

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

Notes

---

---

---

---

---

---

---

---

### ARMA(p, q) Processes

$\{\eta_t\}$  is an ARMA(p, q) process if it satisfies

$$\eta_t - \sum_{i=1}^p \phi_i \eta_{t-i} = Z_t + \sum_{j=1}^q \theta_j Z_{t-j},$$

where  $\{Z_t\}$  is a  $WN(0, \sigma^2)$  process.

- Let  $\phi(B) = 1 - \sum_{i=1}^p \phi_i B^i$  and  $\theta(B) = 1 + \sum_{j=1}^q \theta_j B^j$ . Then we can write it as

$$\phi(B)\eta_t = \theta(B)Z_t$$

- An ARMA(p, q) process  $\{\tilde{\eta}_t\}$  with mean  $\mu$  can be written as

$$\phi(B)(\tilde{\eta}_t - \mu) = \theta(B)Z_t$$

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

Notes

---

---

---

---

---

---

---

---

### A Stationary Solution to the ARMA Equation

A zero-mean ARMA process is stationary if it can be written as a **linear process**, i.e.,  $\eta_t = \psi(B)Z_t$ , where  $\psi(B) = \sum_{j=-\infty}^{\infty} \psi_j B^j$  for an absolutely summable sequence  $\{\psi_j\}$

- This only happens if one can “divide” by  $\phi(B)$ , i.e., it is stationary only if the following makes sense:

$$\begin{aligned} (\phi(B))^{-1} \phi(B)\eta_t &= (\phi(B))^{-1} \theta(B)Z_t \\ \Rightarrow \eta_t &= \underbrace{\frac{\theta(B)}{\phi(B)}}_{=\psi(B)} Z_t \end{aligned}$$

- Let's forget about  $B$  is the backshift operator and replace it with  $z$ . Now consider whether we can divide  $\theta(z)$  by  $\phi(z)$

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

### Notes

---

---

---

---

---

---

---

---

---

---

### Roots of the AR Characteristic Polynomial and Stationarity

- A root of the polynomial  $f(z) = \sum_{j=0}^p a_j z^j$  is a value  $\xi$  such that  $f(\xi) = 0 \Rightarrow$  it can be real-valued  $\mathbb{R}$  or complex-valued  $\mathbb{C}$
- For example, a root can take the form  $\xi = a + bi$  for real number  $a$  and  $b$ . The **modulus** of a complex number  $|\xi|$  is defined by

$$|\xi| = \sqrt{a^2 + b^2}$$

- For any ARMA( $p, q$ ) process, a **stationary** and **unique** solution exists if and only if

$$\phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p \neq 0,$$

for all  $|z| = 1 \Rightarrow$  **None of the roots of the AR characteristic equation have a modulus of exactly 1**

**Note:** Stationarity of the ARMA process has nothing to do with the MA polynomial!!

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

### Notes

---

---

---

---

---

---

---

---

---

---

### AR(4) Example

Consider the following AR(4) process

$$\eta_t = 2.7607\eta_{t-1} - 3.8106\eta_{t-2} + 2.6535\eta_{t-3} - 0.9238\eta_{t-4} + Z_t,$$

the AR characteristic polynomial is

$$\phi(z) = 1 - 2.7607z + 3.8106z^2 - 2.6535z^3 + 0.9238z^4$$

- Hard to find the roots of  $\phi(z)$  –we use the `polyroot` function in R:
- Use `Mod` in R to calculate the modulus of the roots
- **Conclusion:**

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

### Notes

---

---

---

---

---

---

---

---

---

---

### Causal ARMA Processes

An ARMA process is **causal** if there exists constants  $\{\psi_j\}$  with  $\sum_{j=0}^{\infty} |\psi_j| < \infty$  and  $\eta_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j}$ , that is, we can write  $\{\eta_t\}$  as an MA( $\infty$ ) process depending **only on the current and past values of  $\{Z_t\}$**

- Equivalently, an ARMA process is **causal** if and only if

$$\phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p \neq 0,$$

for all  $|z| \leq 1 \Rightarrow$  **None of the roots of the AR characteristic equation have a modulus less than 1**

- The previous AR(4) example is **causal** since each zero,  $\xi$ , of  $\phi(\cdot)$  is such that  $|\xi| > 1$

**Note:** The causality of the ARMA process depends **only on the AR polynomial!**

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

### Notes

---

---

---

---

---

---

---

---

---

---

### Invertible ARMA Processes

An ARMA process is **invertible** if there exists constants  $\{\pi_j\}$  with  $\sum_{j=0}^{\infty} |\pi_j| < \infty$  and

$$Z_t = \sum_{j=0}^{\infty} \pi_j \eta_{t-j},$$

that is, we can write  $\{Z_t\}$  as an AR( $\infty$ ) process depending **only on the current and past values of  $\{\eta_t\}$**

- A process is **invertible** if and only if

$$\theta(z) = 1 + \theta_1 z + \dots + \theta_q z^q \neq 0,$$

for all  $|z| \leq 1 \Rightarrow$  **None of the roots of the MA characteristic equation have a modulus less than 1**

- An ARMA process

$$\eta_t - 0.5\eta_{t-1} = Z_t + 0.4Z_{t-1},$$

with  $\phi(z) = 1 - 0.5z$  and  $\theta(z) = 1 + 0.4z$  has a root of the MA characteristic polynomial at  $z = \frac{-1}{0.4} = -2.5$

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

### Notes

---

---

---

---

---

---

---

---

---

---

### Review of the Autocorrelation Function (ACF)

The **autocorrelation function (ACF)** measures the correlation of a **stationary** time series  $\eta_t$  with its own lagged values

- The theoretical ACF for MA processes can be computed as  $\rho(h) = \frac{\sum_{j=0}^q \theta_j \theta_{j+h}}{\sum_{j=0}^q \theta_j^2}$ , and via the **Yule-Walker equation** for AR processes

- The ACF is useful in identifying the MA(q) order, as it cuts off after lag  $q$

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

### Notes

---

---

---

---

---

---

---

---

---

---

## Partial Autocorrelation Functions (PACF)

The **partial autocorrelation function (PACF)** represents the partial correlation of a stationary time series  $\{\eta_t\}$  with its own lagged values, **while regressing out the effects of the time series at all shorter lags**

- The PACF at lag  $h$  is the autocorrelation between  $\eta_t$  and  $\eta_{t+h}$  with the linear dependence between  $\eta_t$  and  $\eta_{t+1}, \dots, \eta_{t+h-1}$  removed
- PACF plots are a commonly used tool for **identifying the order of an AR model**, as the theoretical PACF “shuts off” past the order of the model (see an example on the next slide)
- One can use the function `pacf` in R to plot the PACF

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

Notes

---

---

---

---

---

---

---

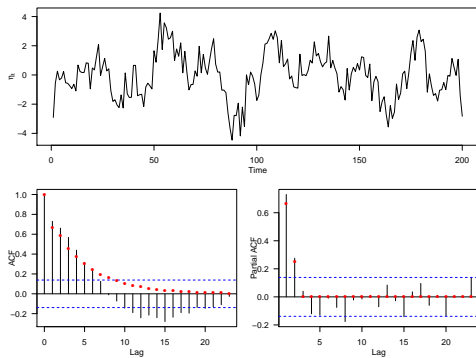
---

---

---

## An Example of PACF Plot

$$\eta_t - 0.5\eta_{t-1} - 0.25\eta_{t-2} = Z_t$$



The theoretical ACF decays exponentially, while the PACF cuts off at lag 2

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

Notes

---

---

---

---

---

---

---

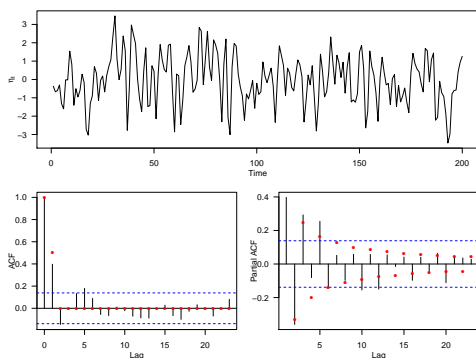
---

---

---

## PACF Plot for a MA Process

$$\eta_t = Z_t + Z_{t-1}$$



The theoretical ACF cuts off at lag 1, while the PACF decays exponentially

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

Notes

---

---

---

---

---

---

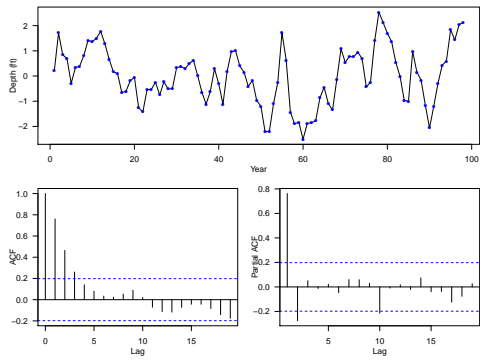
---

---

---

---

### Lake Huron Series PACF Plot



We can use both ACF and PACF plots to identify the potential ARMA model order

**ARMA Models: Properties, Identification, and Estimation**

**PROPERTIES OF ARMA MODELS**

Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

9.13

### Notes

---

---

---

---

---

---

---

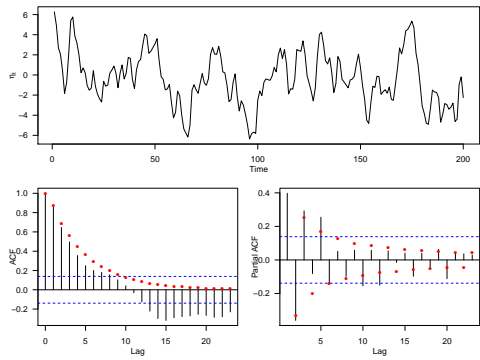
---

---

---

### PACF Plot for a ARMA Process

$$\eta_t - 0.5\eta_{t-1} - 0.25\eta_{t-2} = Z_t + Z_{t-1}$$



Both the theoretical ACF and PACF decay exponentially

**ARMA Models: Properties, Identification, and Estimation**

**PROPERTIES OF ARMA MODELS**

Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

9.14

### Notes

---

---

---

---

---

---

---

---

---

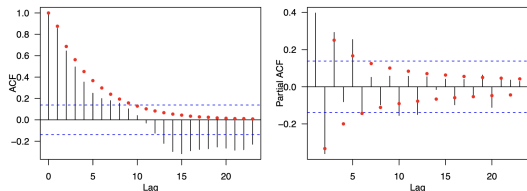
---

### Identifying Plausible Stationary ARMA Models

We can use the sample ACF and PACF to help identify plausible models:

Model	ACF	PACF
MA( $q$ )	cuts off after lag $q$	tails off exponentially
AR( $p$ )	tails off exponentially	cuts off after lag $p$

For ARMA( $p, q$ ) we will see a combination of the above



**ARMA Models: Properties, Identification, and Estimation**

**PROPERTIES OF ARMA MODELS**

Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

9.15

### Notes

---

---

---

---

---

---

---

---

---

---

### Estimation of the ARMA Process Parameters

Suppose we choose a ARMA( $p, q$ ) model for  $\{\eta_t\}$

- Need to estimate the  $p + q + 1$  parameters:
  - AR component  $\{\phi_1, \dots, \phi_p\}$
  - MA component  $\{\theta_1, \dots, \theta_q\}$
  - $\text{Var}(Z_t) = \sigma^2$
- One strategy:
  - Do some preliminary estimation of the model parameters (e.g., via [Yule-Walker estimates](#))
  - Follow-up with [maximum likelihood estimation](#) with Gaussian assumption

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

Notes

---

---

---

---

---

---

---

---

---

---

### The Yule-Walker Method

Suppose  $\eta_t$  is a causal AR( $p$ ) process

$$\eta_t - \phi_1\eta_{t-1} - \dots - \phi_p\eta_{t-p} = Z_t$$

To estimate the parameters  $\{\phi_1, \dots, \phi_p\}$ , we use a [method of moments](#) estimation scheme:

- Let  $h = 0, 1, \dots, p$ . We multiply  $\eta_{t-h}$  to both sides

$$\eta_t\eta_{t-h} - \phi_1\eta_{t-1}\eta_{t-h} - \dots - \phi_p\eta_{t-p}\eta_{t-h} = Z_t\eta_{t-h}$$

- Taking expectations:

$$\mathbb{E}(\eta_t\eta_{t-h}) - \phi_1\mathbb{E}(\eta_{t-1}\eta_{t-h}) - \dots - \phi_p\mathbb{E}(\eta_{t-p}\eta_{t-h}) = \mathbb{E}(Z_t\eta_{t-h}),$$

we get

$$\gamma(h) - \phi_1\gamma(h-1) - \dots - \phi_p\gamma(h-p) = \mathbb{E}(Z_t\eta_{t-h})$$

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

Notes

---

---

---

---

---

---

---

---

---

---

### The Yule-Walker Equations

- When  $h = 0$ ,  $\mathbb{E}(Z_t\eta_{t-h}) = \text{Cov}(Z_t, \eta_t) = \sigma^2$  (Why?)  
Therefore, we have

$$\gamma(0) - \sum_{j=1}^p \phi_j\gamma(j) = \sigma^2$$

- When  $h > 0$ ,  $Z_t$  is uncorrelated with  $\eta_{t-h}$  (because the [assumption of causality](#)), thus  $\mathbb{E}(Z_t\eta_{t-h}) = 0$  and we have

$$\gamma(h) - \sum_{j=1}^p \phi_j\gamma(h-j) = 0, \quad h = 1, 2, \dots, p$$

- The [Yule-Walker estimates](#) are the solution of these equations when we replace  $\gamma(h)$  by  $\hat{\gamma}(h)$

ARMA Models: Properties, Identification, and Estimation



Properties of ARMA Models: Stationarity, Causality, and Invertibility

Tentative Model Identification Using ACF and PACF

Parameter Estimation

Notes

---

---

---

---

---

---

---

---

---

---

## The Yule-Walker Equations in Matrix Form

Let  $\hat{\phi} = (\hat{\phi}_1, \dots, \hat{\phi}_p)^T$  be an estimate for  $\phi = (\phi_1, \dots, \phi_p)^T$  and let

$$\hat{\Gamma} = \begin{bmatrix} \hat{\gamma}(0) & \hat{\gamma}(1) & \dots & \hat{\gamma}(p-1) \\ \hat{\gamma}(1) & \hat{\gamma}(0) & \dots & \hat{\gamma}(p-2) \\ \vdots & \vdots & \ddots & \vdots \\ \hat{\gamma}(p-1) & \hat{\gamma}(p-2) & \dots & \hat{\gamma}(0) \end{bmatrix}.$$

Then the **Yule-Walker estimates** of  $\phi$  and  $\sigma^2$  are

$$\hat{\phi} = \hat{\Gamma}^{-1} \hat{\gamma},$$

and

$$\hat{\sigma}^2 = \hat{\gamma}(0) - \hat{\phi}^T \hat{\gamma},$$

where  $\hat{\gamma} = (\hat{\gamma}(1), \dots, \hat{\gamma}(p))^T$

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

9.19

Notes

---

---

---

---

---

---

---

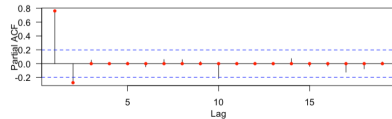
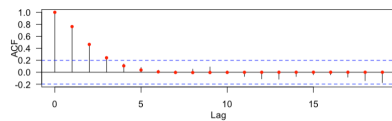
---

---

---

## Lake Huron Example in R

```
## {r}
Yw_est <- ar(lm$residuals, aic = F, order.max = 2, method = "yw")
# plot sample and estimated acf/pacf
par(las = 1, mgp = c(2.2, 1, 0), mar = c(3.6, 3.6, 0.6, 0.6), mfrow = c(2, 1))
acf(lm$residuals)
acf_YwEst <- ARMAacf(ar = Yw_est$ar, lag.max = 23)
points(0:23, acf_YwEst, col = "red", pch = 16, cex = 0.8)
pacf(lm$residuals)
pacf_YwEst <- ARMAacf(ar = Yw_est$ar, lag.max = 23, pacf = T)
points(1:23, pacf_YwEst, col = "red", pch = 16, cex = 0.8)
##
```



ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

9.20

Notes

---

---

---

---

---

---

---

---

---

---

## Remarks on the Yule-Walker Method

- For large sample size, **Yule-Walker estimator** have (approximately) the same sampling distribution as **maximum likelihood estimator (MLE)**, but with small sample size Yule-Walker estimator can be far less efficient than the MLE
- The Yule-Walker method is a **poor procedure for MA(q) and ARMA(p,q) processes with q > 0** (see Cryer Chan 2008, p. 150-151)
- We move on the more versatile and popular method for estimating ARMA(p,q) parameters—**maximum likelihood estimation**<sup>1</sup>

<sup>1</sup>See **Least Squares Estimation** in Chapter 7.2 of Cryer and Chan (2008).

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

9.21

Notes

---

---

---

---

---

---

---

---

---

---

## Maximum Likelihood Estimation

- The setup:
  - Model:  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  has joint probability density function  $f(\mathbf{x}; \boldsymbol{\omega})$  where  $\boldsymbol{\omega} = (\omega_1, \omega_2, \dots, \omega_p)$  is a vector of  $p$  parameters
  - Data:  $\mathbf{x} = (x_1, x_2, \dots, x_n)$

- The **likelihood function** is defined as the the "likelihood" of the data,  $\mathbf{x}$ , given the parameters,  $\boldsymbol{\omega}$

$$L_n(\boldsymbol{\omega}) = f(\mathbf{x}; \boldsymbol{\omega})$$

- The **maximum likelihood estimate** (MLE) is the value of  $\boldsymbol{\omega}$  which maximizes the likelihood,  $L_n(\boldsymbol{\omega})$ , of the data  $\mathbf{x}$ :

$$\hat{\boldsymbol{\omega}} = \underset{\boldsymbol{\omega}}{\operatorname{argmax}} L_n(\boldsymbol{\omega}).$$

It is equivalent (and often easier) to maximize the log likelihood,

$$\ell_n(\boldsymbol{\omega}) = \log L_n(\boldsymbol{\omega})$$

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

9.22

Notes

---

---

---

---

---

---

---

---

---

---

## The MLE for an i.i.d. Gaussian Process

Suppose  $\{X_t\}$  be a Gaussian i.i.d. process with mean  $\mu$  and variance  $\sigma^2$ . We observe a time series  $\mathbf{x} = (x_1, \dots, x_n)^T$ .

- The likelihood function is

$$\begin{aligned} L_n(\mu, \sigma^2) &= f(\mathbf{x}|\mu, \sigma^2) \\ &= \prod_{t=1}^n f(x_t|\mu, \sigma) \\ &= \prod_{t=1}^n \left\{ \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{(x_t - \mu)^2}{2\sigma^2}\right] \right\} \\ &= (2\pi)^{-n/2} (\sigma^2)^{-n/2} \exp\left[-\frac{\sum_{t=1}^n (x_t - \mu)^2}{2\sigma^2}\right] \end{aligned}$$

- The log-likelihood function is

$$\begin{aligned} \ell_n(\mu, \sigma^2) &= \log L_n(\mu, \sigma^2) \\ &= -\frac{n}{2} \log(2\pi) - \frac{n}{2} \log(\sigma^2) - \frac{\sum_{t=1}^n (x_t - \mu)^2}{2\sigma^2} \end{aligned}$$

$$\Rightarrow \hat{\mu}_{\text{MLE}} = \frac{\sum_{t=1}^n X_t}{n} = \bar{X}, \quad \hat{\sigma}_{\text{MLE}}^2 = \frac{\sum_{t=1}^n (X_t - \bar{X})^2}{n}$$

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

9.23

Notes

---

---

---

---

---

---

---

---

---

---

## Likelihood for Stationary Gaussian Time Series Models

Suppose  $\{X_t\}$  be a zero **stationary Gaussian** time series with ACVF  $\gamma(h)$ . If  $\gamma(h)$  depends on  $p$  parameters,  $\boldsymbol{\omega} = (\omega_1, \dots, \omega_p)$

- The likelihood of the data  $\mathbf{x} = (x_1, \dots, x_n)$  given the parameters  $\boldsymbol{\omega}$  is

$$L_n(\boldsymbol{\omega}) = (2\pi)^{-n/2} |\boldsymbol{\Gamma}|^{-1/2} \exp\left(-\frac{1}{2} \mathbf{x}^T \boldsymbol{\Gamma}^{-1} \mathbf{x}\right),$$

where  $\boldsymbol{\Gamma}$  is the **covariance matrix** of  $\mathbf{X} = (X_1, \dots, X_n)^T$ ,  $|\boldsymbol{\Gamma}|$  is the **determinant** of the matrix  $\boldsymbol{\Gamma}$ , and  $\boldsymbol{\Gamma}^{-1}$  is the **inverse** of the matrix  $\boldsymbol{\Gamma}$

- The log-likelihood is

$$\ell_n(\boldsymbol{\theta}) = -\frac{n}{2} \log(2\pi) - \frac{1}{2} \log |\boldsymbol{\Gamma}| - \frac{1}{2} \mathbf{x}^T \boldsymbol{\Gamma}^{-1} \mathbf{x}$$

Typically need to solve it numerically

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

9.24

Notes

---

---

---

---

---

---

---

---

---

---



## Decomposing Joint Density into Conditional Densities

A joint distribution can be represented as the product of conditionals and a marginal distribution

- The simple version for  $n = 2$  is:

$$f(x_1, x_2) = f(x_2|x_1)f(x_1)$$

- Extending for general  $n$  we get the following expression for the likelihood:

$$L_n(\theta) = f(\mathbf{x}; \theta) = f(x_1) \prod_{t=2}^n f(x_t|x_{t-1}, \dots, x_1; \theta),$$

and the log-likelihood is

$$\ell_n(\theta) = \log f(\mathbf{x}; \theta) = \log(f(x_1)) + \sum_{t=2}^n \log f(x_t|x_{t-1}, \dots, x_1; \theta).$$

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

9.25

Notes

---

---

---

---

---

---

---

---

---

---

## AR(1) Log-likelihood

Let  $\{\eta_1, \eta_2, \dots, \eta_n\}$  be a realization of a zero-mean stationary AR(1) Gaussian time series. Let  $\theta = (\phi, \sigma^2)$

$$\ell_n(\theta) = \underbrace{\log(f(\eta_1))}_{\ell_{n,1}} + \underbrace{\sum_{t=2}^n \log f(\eta_t|\eta_{t-1}, \dots, \eta_1; \theta)}_{\ell_{n,2}}.$$

Note that for  $t \geq 2$ ,  $f(\eta_t|\eta_{t-1}, \dots, \eta_1) = f(\eta_t|\eta_{t-1})$ , where  $[\eta_t|\eta_{t-1}] \sim N(\phi\eta_{t-1}, \sigma^2) \Rightarrow \ell_{n,2} =$

$$-\frac{(n-1)}{2} \log 2\pi - \frac{(n-1)}{2} \log \sigma^2 - \frac{\sum_{t=2}^n (\eta_t - \phi\eta_{t-1})^2}{2\sigma^2}$$

Also, we know  $[\eta_1] \sim N(0, \frac{\sigma^2}{1-\phi^2}) \Rightarrow \ell_{1,n} =$

$$-\frac{\log 2\pi}{2} - \frac{\log \sigma^2}{2} + \frac{\log(1-\phi^2)}{2} - \frac{(1-\phi^2)\eta_1^2}{2\sigma^2}$$

$$\Rightarrow \ell_n(\theta) = -\frac{n}{2} \log 2\pi - \frac{n}{2} \log \sigma^2 - \frac{\sum_{t=2}^n (\eta_t - \phi\eta_{t-1})^2}{2\sigma^2} + \frac{\log(1-\phi^2)}{2} - \frac{(1-\phi^2)\eta_1^2}{2\sigma^2}$$

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

9.26

Notes

---

---

---

---

---

---

---

---

---

---

## AR(1) Log-likelihood Cont'd

$$\ell_n(\theta) = -\frac{n}{2} \log 2\pi - \frac{n}{2} \log \sigma^2 + \frac{\log(1-\phi^2)}{2} - \frac{S(\phi)}{2\sigma^2},$$

where  $S(\phi) = \sum_{t=2}^n (\eta_t - \phi\eta_{t-1})^2 + (1-\phi^2)\eta_1^2$

- For given value of  $\phi$ ,  $\ell_n(\phi, \sigma^2)$  can be maximized analytically with respect to  $\sigma^2$

$$\hat{\sigma}^2 = \frac{S(\hat{\phi})}{n}$$

- Estimation of  $\phi$  can be simplified by maximizing the **conditional sum-of-squares** ( $\sum_{t=2}^n (\eta_t - \phi\eta_{t-1})^2$ )

ARMA Models:  
Properties,  
Identification,  
and Estimation



Properties of  
ARMA Models:  
Stationarity,  
Causality, and  
Invertibility

Tentative Model  
Identification Using  
ACF and PACF

Parameter  
Estimation

9.27

Notes

---

---

---

---

---

---

---

---

---

---

