# Lecture 9 Regression with Time Series Errors Readings: BD16 Chapter 6.6; SS17 Chapter 3.8

MATH 8090 Time Series Analysis Week 9





Time Series Regression Models

Generalized Least Squares Regression

ake Huron Example

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# Agenda







Regression with Time Series Errors



Time Series Regression Models

Generalized Least Squares Regression

# **Time Series Regression**

Suppose we have the following time series model for  $\{Y_t\}$ :

$$Y_t = m_t + \eta_t$$

where

- $m_t$  captures the mean of  $\{Y_t\}$ , i.e.,  $\mathbb{E}(Y_t) = m_t$
- $\{\eta_t\}$  is a zero mean stationary process with ACVF  $\gamma_{\eta}(\cdot)$

The component  $\{m_t\}$  may depend on time t, or possibly on other explanatory series





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## Example Models for $m_t$ : Trends and Seasonality

- Constant trend model: For each t let  $m_t = \beta_0$  for some unknown parameter  $\beta_0$
- Simple linear regression: For unknown parameters  $\beta_0$  and  $\beta_1$ ,

$$m_t = \beta_0 + \beta_1 x_t,$$

where  $\{x_t\}$  is some explanatory variable indexed in time (may just be a function of time or could be other series)

• Harmonic regression: For each t let

$$m_t = A\cos(2\pi ft + \phi),$$

where A > 0 is the amplitude (an unknown parameter), f > 0 is the frequency of the sinusoid (usually known), and  $\phi \in (-\pi, \pi]$  is the phase (usually unknown). We can rewrite this model as

$$m_t = \beta_0 x_{1,t} + \beta_1 x_{2,t},$$

where  $x_{1,t} = \cos(2\pi ft)$  and  $x_{2,t} = \sin(2\pi ft)$ 

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#### The Multiple Linear Regression Model

Suppose there are p explanatory series  $\{x_{j,t}\}_{j=1}^p,$  the time series model for  $\{Y_t\}$  is

$$Y_t = m_t + \eta_t,$$

where

$$m_t = \beta_0 + \sum_{j=1}^p \beta_j x_{j,t},$$

and  $\{\eta_t\}$  is a mean zero stationary process with ACVF  $\gamma_{\eta}(\cdot)$ We can write the linear model in matrix notation:

$$Y = X\beta + \eta$$
,

where  $\boldsymbol{Y} = (Y_1, \dots, Y_n)^T$  is the observation vector, the coefficient vector is  $\boldsymbol{\beta} = (\beta_0, \beta_1, \dots, \beta_p)^T$ ,  $\boldsymbol{\eta} = (\eta_1, \dots, \eta_n)^T$  is the error vector, and the design matrix is

$$\boldsymbol{X} = \begin{bmatrix} 1 & x_{1,1} & x_{2,1} & \cdots & x_{p,1} \\ 1 & x_{1,2} & x_{2,2} & \cdots & x_{p,2} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ 1 & x_{1,n} & x_{2,n} & \cdots & x_{p,n} \end{bmatrix}$$





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# The Model Estimates and Distributional Results for i.i.d. Errors Case

Suppose  $\{\eta_t\}$  is i.i.d.  $N(0, \sigma^2)$ . Then the ordinary least squares (OLS) estimate of  $\beta$  is

$$\hat{\boldsymbol{\beta}}_{ ext{OLS}} = \left( \boldsymbol{X}^T \boldsymbol{X} \right)^{-1} \boldsymbol{X}^T \boldsymbol{Y}$$

with

$$\hat{\sigma}^{2} = \frac{\left(\boldsymbol{Y} - \boldsymbol{X}\hat{\boldsymbol{\beta}}_{\text{OLS}}\right)^{T} \left(\boldsymbol{Y} - \boldsymbol{X}\hat{\boldsymbol{\beta}}_{\text{OLS}}\right)}{n - (p+1)}$$

- Gauss-Markov theorem:  $\hat{\beta}_{OLS}$  is the best linear unbiased estimator (BLUE) of  $\beta$
- We have

$$\hat{\boldsymbol{\beta}}_{\text{OLS}} \sim \mathrm{N}(\boldsymbol{\beta}, \sigma^2 \left( \boldsymbol{X}^T \boldsymbol{X} \right)^{-1})$$

is independent of

$$\frac{(n-(p+1))\hat{\sigma}^2}{\sigma^2} \sim \chi^2_{n-(p+1)}$$





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## Climate Over Past Millennia [Jones & Mann, 2004]



Residuals from a linear regression fit are correlated in time

#### **Generalized Least Squares Regression**

When dealing with time series the errors  $\{\eta_t\}$  are typically correlated in time

Assuming the errors {η<sub>t</sub>} are a stationary Gaussian process, consider the model

$$Y = X\beta + \eta$$
,

where  $\boldsymbol{\eta}$  has a multivariate normal distribution, i.e.,  $\boldsymbol{\eta} \sim N(\boldsymbol{0}, \boldsymbol{\Sigma})$ 

• The generalized least squares (GLS) estimate of  $\beta$  is

$$\hat{\boldsymbol{\beta}}_{\text{GLS}} = \left( \boldsymbol{X}^T \boldsymbol{\Sigma}^{-1} \boldsymbol{X} \right)^{-1} \boldsymbol{X}^T \boldsymbol{\Sigma}^{-1} \boldsymbol{Y},$$

with

$$\sigma^{2} = \frac{\left(\boldsymbol{Y} - \boldsymbol{X}\hat{\boldsymbol{\beta}}_{\text{GLS}}\right)^{T} \left(\boldsymbol{Y} - \boldsymbol{X}\hat{\boldsymbol{\beta}}_{\text{GLS}}\right)}{n - (p+1)}$$

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**Distributional Properties of Estimators** 

Gauss-Markov theorem:  $\beta_{\rm GLS}$  is the best linear unbiased estimator (BLUE) of  $\beta$ 

We have

$$\hat{\boldsymbol{\beta}}_{\text{GLS}} \sim \mathrm{N}(\boldsymbol{\beta}, \sigma^2 \left( \boldsymbol{X}^T \boldsymbol{\Sigma}^{-1} \boldsymbol{X} \right)^T)$$

• The variance of linear combinations of  $\hat{\beta}_{GLS}$  is less than or equal to the variance of linear combinations of  $\hat{\beta}_{OLS}$ , that is:

 $\operatorname{Var}\left(\boldsymbol{c}^{T}\hat{\boldsymbol{\beta}}_{\mathrm{GLS}}\right) \leq \operatorname{Var}\left(\boldsymbol{c}^{T}\hat{\boldsymbol{\beta}}_{\mathrm{OLS}}\right)$ 

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# **Applying GLS In Practice**

The main problem in applying GLS in practice is that  $\Sigma$  depends on  $\phi$ ,  $\theta$ , and  $\sigma^2$  and we have to estimate these

A two-step procedure

- Stimate  $\beta$  by OLS, calculating the residuals  $\hat{\eta} = Y - X \hat{\beta}_{OLS}$ , and fit an ARMA to  $\hat{\eta}$  to get  $\Sigma$
- Pe-estimate  $\beta$  using GLS
- Alternatively, we can consider one-shot maximum likelihood methods





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# Likelihood-based Regression Methods

Model:

$$Y = X\beta + \eta$$
,

where  $\boldsymbol{\eta} \sim N(\boldsymbol{0}, \boldsymbol{\Sigma})$ 

$$\Rightarrow \mathbf{Y} \sim \mathcal{N}(\mathbf{X}\boldsymbol{\beta}, \Sigma)$$

• We maximum the Gaussian likelihood

$$L_{n}(\boldsymbol{\beta}, \boldsymbol{\phi}, \boldsymbol{\theta}, \sigma^{2}) = (2\pi)^{-n/2} |\boldsymbol{\Sigma}|^{-1/2} \exp\left[-\frac{1}{2} \left(\boldsymbol{Y} - \boldsymbol{X}\boldsymbol{\beta}\right)^{T} \boldsymbol{\Sigma}^{-1} \left(\boldsymbol{Y} - \boldsymbol{X}\boldsymbol{\beta}\right)\right]$$

with respect to the regression parameters  $\beta$  and ARMA parameters  $\phi$ ,  $\theta$ ,  $\sigma^2$  simultaneously

 As before, we can re-express the likelihoods using the one-step-ahead predictions



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# An Example: Lake Huron Levels

# Model:

$$Y_t = m_t + \eta_t$$

#### where

 $m_t = \beta_0 + \beta_1 t$  $\{n_t\}$  is some ARMA(p, q) process

- Scientific Question: Is there evidence that the lake level has been changing steadily over the years 1875-1972?
- Statistical Hypothesis:





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#### Fitting Result form the Two-Step Procedure

```
> lm <- lm(LakeHuron ~ years)</pre>
> lm$coefficients
(Intercept)
                    years
625.55491791 -0.02420111
> (MLE_est1 <- arima(lmresiduals, order = c(2, 0, 0),
                     include.mean = FALSE))
+
(all:
arima(x = lmsresiduals, order = c(2, 0, 0), include.mean = FALSE)
Coefficients:
         ar1
                  ar2
     1.0050 -0.2925
s.e. 0.0976 0.1002
```

sigma^2 estimated as 0.4572: log likelihood = -101.26, aic = 208.51





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#### Fitting Result from One-Step MLE

```
> mle <- arima(LakeHuron, order = c(2, 0, 0),
               xreg = cbind(rep(1,length(LakeHuron)), years),
+
               include.mean = FALSE)
+
> mle
(all:
arima(x = LakeHuron, order = c(2, 0, 0), xreq = cbind(rep(1, length(LakeHuron))),
    years), include.mean = FALSE)
Coefficients:
                  ar2 rep(1, length(LakeHuron))
         ar1
      1.0048 -0.2913
                                         620.5115
S. P. 0.0976
              0.1004
                                          15.5771
        years
      -0.0216
s.e. 0.0081
sigma<sup>2</sup> estimated as 0.4566: log likelihood = -101.2, aic = 212.4
```





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#### **MLE Fit Diagnostics**







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Lake Huron Example

Box-Ljung test

data: y X-squared = 6.2088, df = 19, p-value = 0.9974

# **Comparing Confidence Intervals**

## > confint(lm)

2.5 % 97.5 % (Intercept) 610.14291793 640.9669179 -0.03221272 -0.0161895 vears > confint(MLE\_est1) 2.5 % 97.5 % ar1 0.8137180 1.19630830 ar2 -0.4888881 -0.09606208 > confint(mle) 2.5 % 97.5 % ar1 0.81348340 1.196124084 ar2 -0.48806617 -0.094573470 rep(1, length(LakeHuron)) 589.98093574 651.042054268 -0.03744268 -0.005694972 years





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