

# Lecture 24

## Computer Experiments & Principal Component Analysis

STAT 8020 Statistical Methods II  
November 19, 2020

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Clemson University



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### Agenda

- 1 Computer Experiments
- 2 Multivariate Analysis
- 3 Principal component analysis (PCA)



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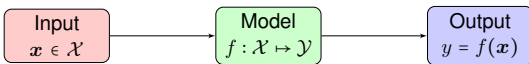
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### What is a Computer Experiment

In some situations it is economically, ethically, or simply not possible to run a **physical experiment**. Instead, the following scenario might be feasible:

- the physical process can be described by a mathematical model (e.g., a system of differential equations)
- computer code (simulator) can be written to compute the response from the mathematical model



In this case, a researcher can conduct a **computer experiment** by running the computer code, which serves as a proxy for the physical process, to compute a "response" at any combination of values of the inputs



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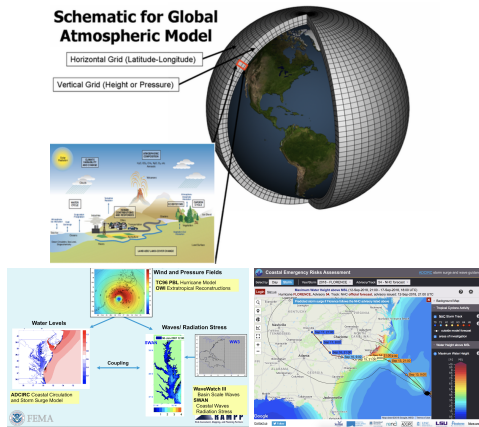
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## Examples of Computer Models



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## Computer Experiments vs. Physical Experiments

- “Experimental results are believed by everyone, except for the person who ran the experiment”
- “Computational results are believed by no one, except the person who wrote the code”

Replication, randomization and blocking are irrelevant for a computer experiment because many **computer codes are deterministic** and **all the inputs to the code are known and can be controlled**

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## Design & Analysis of Computer Experiments

- **Design:**  
where to make the runs, i.e., the selection of inputs  $\{\mathbf{x}_i\}_{i=1}^n$  where  $\mathbf{x}_i = (x_{1,i}, x_{2,i}, \dots, x_{d,i})$
- **Analysis:**  
fit a statistical model using the model inputs-output  $\{y_i, \mathbf{x}_i\}_{i=1}^n$  to “emulate” the simulator and to quantify the prediction uncertainty for  $y(\mathbf{x}_{\text{new}})$ , usually via a **Gaussian Process Model**  $\text{GP}(m(\cdot), K(\cdot, \cdot))$ , where
  - $m(\mathbf{x}) = E[y(\mathbf{x})]$  is the **mean function**
  - $K(\mathbf{x}, \mathbf{x}') = \text{Cov}(y(\mathbf{x}), y(\mathbf{x}'))$  is the **covariance function**

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## An Overview of Multivariate Analysis

- In many studies, observations are collected on **several variables** on each experimental/observational unit
- **Multivariate analysis** is a collection of statistical methods for analyzing these multivariate data sets
- **Common Objectives**
  - Dimensionality reduction
  - Classification
  - Grouping (Clustering)



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## Multivariate Data

We display a multivariate data that contains  $n$  units on  $p$  variables using a matrix

$$\mathbf{X} = \begin{pmatrix} X_{1,1} & X_{2,1} & \cdots & X_{p,1} \\ X_{1,2} & X_{2,2} & \cdots & X_{p,2} \\ \vdots & \cdots & \ddots & \vdots \\ X_{1,n} & X_{2,n} & \cdots & X_{p,n} \end{pmatrix}$$

## Summary Statistics

- **Mean Vector:**  $\bar{\mathbf{X}} = (\bar{X}_1, \bar{X}_2, \dots, \bar{X}_p)^T$
- **Covariance Matrix:**  $\Sigma = \{\sigma_{ij}\}_{i,j=1}^p$ , where  $\sigma_{ii} = \text{Var}(X_i)$ ,  $i = 1, \dots, p$  and  $\sigma_{ij} = \text{Cov}(X_i, X_j)$ ,  $i \neq j$

Next, we are going to introduce **Principal Component Analysis (PCA)**, a useful tool for conducting **dimension reduction**



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## Example: Monthly Sea Surface Temperatures



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## Sea Surface Temperatures and Anomalies

- The “data” are gridded at a  $2^\circ$  by  $2^\circ$  resolution from  $124^\circ E - 70^\circ W$  and  $30^\circ S - 30^\circ N$ . The dimension of this SST data set is  $2303$  (number of grid points in space)  $\times$   $552$  (monthly time series from 1970 Jan. to 2015 Dec.)
- Sea-surface temperature anomalies are the temperature differences from the climatology (i.e. long-term monthly mean temperatures)
- We will demonstrate the use of Empirical Orthogonal Function (EOF) analysis to uncover the low-dimensional structure of this spatio-temporal data set

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## The Empirical Orthogonal Function (EOF) Decomposition

Empirical orthogonal functions (EOFs) are the geophysicist's terminology for the eigenvectors in the eigen-decomposition of an empirical covariance matrix. In its discrete formulation, EOF analysis is simply **Principal Component Analysis (PCA)**. EOFs are usually used

- To find principal spatial structures
- To reduce the dimension (spatially or temporally) in large spatio-temporal datasets

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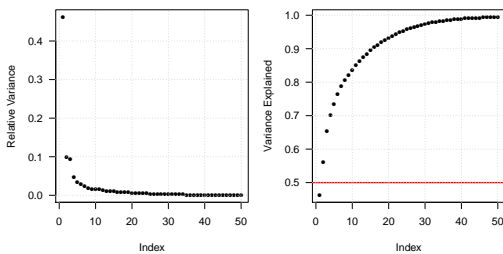
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## Screen Plot for EOFs



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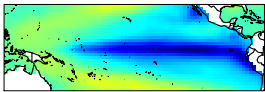
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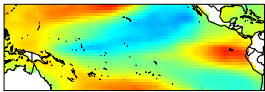
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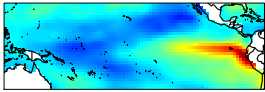
**Perform EOF Decomposition and Plot the First Three Modes**



EOF1: The classic ENSO pattern



EOF2: A modulation of the center



EOF3: Messing with the coast of SA and the Northern Pacific.

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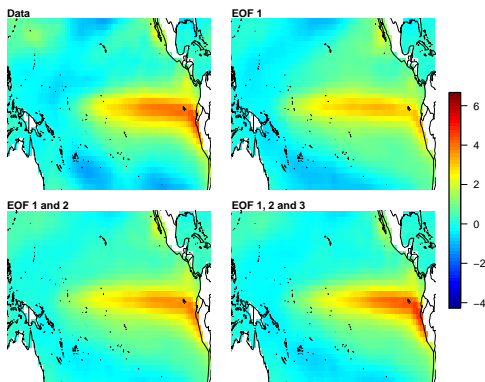
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**1998 Jan El Niño Event**



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**Principal Component Analysis**

Given a random sample from a  $p$ -dimensional random vector  $X_i = \{X_{1,i}, X_{2,i}, \dots, X_{p,i}\}$ ,  $i = 1, \dots, n$

- Dimension reduction technique
  - Large number of variables ( $p$ )
  - Number of variables ( $p$ ) may be greater than number of observations ( $n$ )
- Create new, uncorrelated variables (principal components) for the follow up analysis
  - Principal Component Regression
  - Interpretation of principal components can be difficult in some situations

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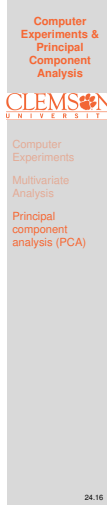
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## Finding Principal Components

Principal Components (PC) are uncorrelated **linear combinations**  $\tilde{X}_1, \tilde{X}_2, \dots, \tilde{X}_p$  determined sequentially, as follows:

- 1 The first PC is the linear combination  $\tilde{X}_1 = \mathbf{c}_1^T \mathbf{X} = \sum_{i=1}^p c_{1i} X_i$  that maximize  $\text{Var}(\tilde{X}_1)$  subject to  $\mathbf{c}_1^T \mathbf{c}_1 = 1$
- 2 The second PC is the linear combination  $\tilde{X}_2 = \mathbf{c}_2^T \mathbf{X} = \sum_{i=1}^p c_{2i} X_i$  that maximize  $\text{Var}(\tilde{X}_2)$  subject to  $\mathbf{c}_2^T \mathbf{c}_2 = 1$  and  $\mathbf{c}_2^T \mathbf{c}_1 = 0$
- ⋮
- 3 The  $j_{th}$  PC is the linear combination  $\tilde{X}_j = \mathbf{c}_j^T \mathbf{X} = \sum_{i=1}^p c_{ji} X_i$  that maximize  $\text{Var}(\tilde{X}_j)$  subject to  $\mathbf{c}_j^T \mathbf{c}_j = 1$  and  $\mathbf{c}_j^T \mathbf{c}_k = 0 \forall k < j$



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## Principal Components

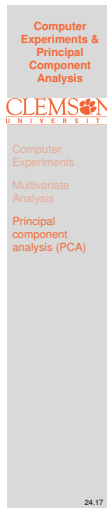
- Let  $\Sigma$ , the covariance matrix of  $\mathbf{X}$ , have eigenvalue-eigenvector pairs  $(\lambda_i, \mathbf{e}_i)_{i=1}^p$  with  $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_p \geq 0$ . Then, the  $k_{th}$  principal component is given by

$$\tilde{X}_k = \mathbf{e}_k^T \mathbf{X} = e_{k1} X_1 + e_{k2} X_2 + \dots + e_{kp} X_p$$

- Then,

$$\text{Var}(\tilde{X}_i) = \lambda_i, \quad i = 1, \dots, p$$

$$\text{Cov}(\tilde{X}_j, \tilde{X}_k) = 0, \quad \forall j \neq k$$



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## PCA and Proportion of Variance Explained

- It can be shown that

$$\sum_{i=1}^p \text{Var}(\tilde{X}_i) = \lambda_1 + \lambda_2 + \dots + \lambda_p = \sum_{i=1}^p \text{Var}(X_i)$$

- The proportion of the total variance associated with the  $k_{th}$  principal component is given by

$$\frac{\lambda_k}{\lambda_1 + \lambda_2 + \dots + \lambda_p}$$

- If a large proportion of the total population variance (say 80% or 90%) is explained by the first k PCs, then we can restrict attention to the first k PCs without much loss of information



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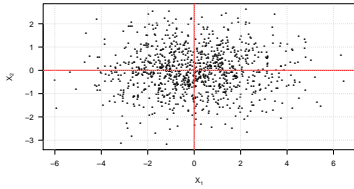
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### Toy Example 1

Suppose we have  $\mathbf{X} = (X_1, X_2)^T$  where  $X_1 \sim N(0, 4)$ ,  $X_2 \sim N(0, 1)$  are independent

- Total variation =  $\text{Var}(X_1) + \text{Var}(X_2) = 5$
- $X_1$  axis explains 80% of total variation
- $X_2$  axis explains the remaining 20% of total variation



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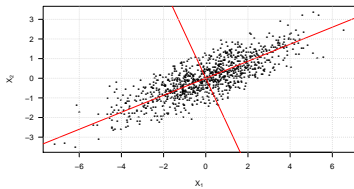
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### Toy Example 2

Suppose we have  $\mathbf{X} = (X_1, X_2)^T$  where  $X_1 \sim N(0, 4)$ ,  $X_2 \sim N(0, 1)$  and  $\text{Cor}(X_1, X_2) = 0.8$

- Total variation =  $\text{Var}(X_1) + \text{Var}(X_2) = \text{Var}(\tilde{X}_1) + \text{Var}(\tilde{X}_2) = 5$
- $\tilde{X}_1 = .9175X_1 + .3975X_2$  explains 93.9% of total variation
- $\tilde{X}_2 = .3975X_1 - .9175X_2$  explains the remaining 6.1% of total variation



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